IN THE CLAIMS:

Please cancel claims 2-4, 7, 15-46, and 48-49 and amend the claims as follows:

1. (Currently Amended) An apparatus for handling a tubular, comprising:

a first gripping member operatively coupled to a second gripping member to retain the tubular;

the first gripping member including a first jaw; and

the second gripping member including a second jaw, wherein ~~at least~~ one of the jaws has an actuator to move the jaw independent of the gripping member in order to apply a force to the tubular and a second actuator to cause the first and second gripping members to engage the tubular, wherein the second actuator comprises a spindle.

2-4. (Cancelled)

5. (Currently Amended) The apparatus of claim [[4]] 1, wherein rotating the spindle moves the first gripping member relative to the second gripping member.

6. (Currently Amended) The apparatus of claim [[2]] 1, wherein the second actuator is adapted to resist elastic deformation.

7. (Cancelled)

8. (Previously Presented) The apparatus of claim 6, wherein the second actuator includes one or more arcuate contact surfaces.

9. (Currently Amended) The apparatus of claim [[2]] 1, wherein the force is applied by a cylinder.

10. (Currently Amended) The apparatus of claim [[2]] 1, wherein at least one of the first and second jaws includes a spherical bearing.

11. (Currently Amended) The apparatus of claim [[2]] 1, further comprising one or more force distributors comprising pendulum bolts attached to the first and second gripping members.

12. (Previously Presented) The apparatus of claim 1, wherein the actuator is a hydraulic cylinder.

13. (Original) The apparatus of claim 1, wherein at least one of the first and second jaws includes a spherical bearing.

14. (Previously Presented) The apparatus of claim 1, further comprising one or more force distributors comprising pendulum bolts connecting the first and second jaw to the first and second gripping members.

15-46. (Cancelled)

47. (Previously Presented) The apparatus of claim 1, further comprising the first gripping member is rotatable relative to the second gripping member.

48-49. (Cancelled)

50. (Previously Presented) The apparatus of claim 2, wherein the second actuator is adapted to apply a second force to the tubular.

Please add the following new claims:

51. (New) An adjustable tubular handling assembly, comprising:

a wrenching tong, for gripping and applying torque to a tubular, wherein the wrenching tong comprises:

two clamping members being moveable toward and away from each other in a substantially parallel plane, wherein at least one of the clamping members is actuatable;

an actuator for actuating at least one of the clamping members ;

a jaw attachable to one of the clamping members for gripping the tubular;

a second actuator for actuating the jaw;

a wrenching member for rotating the wrenching tong; and

a backup tong.

52. (New) The adjustable tubular handling assembly of claim 51, wherein the actuator moves the clamping members for gripping the tubular.

53. (New) The adjustable tubular handling assembly of claim 51, wherein one of the clamping members is moveable and one is a fixed member.

54. (New) The adjustable tubular handling assembly of claim 53 wherein the second actuator is on the fixed member.

55. (New) The adjustable tubular handling assembly of claim 51, wherein the actuator is a spindle.

56. (New) The adjustable tubular handling assembly of claim 55, wherein the second actuator is a piston and cylinder to fluidly actuate the jaw.

57. (New) The adjustable tubular handling assembly of claim 56, wherein the wrenching member is a second piston and cylinder to fluidly actuate the wrenching tong.

58. (New) The adjustable tubular handling assembly of claim 51, further comprising the backup tong comprising:

two backup clamping members being moveable toward and away from each other in a substantially parallel plane, wherein at least one of the backup clamping members is actuatable;

a backup actuator for actuating at least one of the backup clamping members;

a backup jaw attachable to one of the backup clamping members for gripping the tubular; and

a second backup actuator for actuating the jaw.

59. (New) A method for handling a tubular comprising:

providing a wrenching tong, wherein the wrenching tong comprises;

two clamping members;

an actuator for actuating at least one of the clamping members;

a jaw attachable to one of the clamping members;

a second actuator for actuating the jaw; and

a wrenching member for rotating the wrenching tong;

actuating the actuator and moving at least one of the clamping members thereby gripping the tubular with the jaw;

actuating the second actuator thereby applying an additional gripping force to the tubular with the jaws;

rotating the tubular using the wrenching member.

60. (New) The method of claim 59, further comprising completing a connection and releasing the tubular.

61. (New) The method of claim 59, further comprising adjusting the two clamping members for a larger diameter tubular.

62. (New) The method of claim 61, further comprising actuating the actuator and moving at least one of the clamping members thereby gripping the larger diameter tubular with the jaw.

63. (New) The method of claim 59, further comprising adjusting the two clamping members for a smaller diameter tubular.

64. (New) The method of claim 63, further comprising actuating the actuator and moving at least one of the clamping members thereby gripping the smaller diameter tubular with the jaw.

65. (New) The method of claim 59, further comprising gripping the tubular with a backup tong.

66. (New) The method of claim 65, further comprising providing the backup tong wherein the backup tong comprises:

two backup clamping members wherein at least one of the backup clamping members is actuatable;

a backup actuator for actuating at least one of the backup clamping members;

a backup jaw attachable to one of the backup clamping members; and

a second backup actuator for actuating the backup jaw.

67. (New) The method of claim 59, wherein the actuator is a spindle.

68. (New) The method of claim 59, wherein the clamping members define a substantially parallel surfaces that move toward and away from each other when actuating the actuator.